

# Chapter 2: Motion in a Straight Line

## Comprehensive Study Notes

Class 11 Physics - NCERT Based

EXAM SPRINT - Complete Coverage for JEE and NEET Examinations

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### 2.1 INTRODUCTION

#### What is Motion?

**Definition:** Motion is change in position of an object with time.

#### Key Characteristics:

- Universal phenomenon (everything in universe is in motion)
- Relative nature (depends on reference frame)
- Continuous change in position

#### Examples of Motion:

- Walking, running, cycling
- Blood flow in arteries
- Earth's rotation and revolution
- Planetary motion in galaxy

#### Rectilinear Motion

**Definition:** Motion of objects along a straight line

- Also known as one-dimensional motion
- Simplest form of motion to analyze
- Foundation for understanding complex motions

## **Point Object Approximation**

### **Validity Conditions:**

- Object size  $\ll$  distance traveled
- Time duration is reasonable
- Applicable to most real-life situations

### **Examples:**

- Car traveling between cities
- Planet orbiting the sun
- Ball thrown vertically

## **Kinematics vs Dynamics**

**Kinematics:** Study of motion without considering causes **Dynamics:** Study of causes of motion  
(covered in Chapter 4)

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## **2.2 INSTANTANEOUS VELOCITY AND SPEED**

### **Average Velocity Limitations**

- Tells overall motion characteristics
- Doesn't reveal motion details at specific instants
- May miss important motion variations

## Instantaneous Velocity Definition

### Mathematical Definition:

$$v = \lim(\Delta t \rightarrow 0) \Delta x / \Delta t = dx/dt$$

### Physical Meaning:

- Velocity at a specific instant
- Rate of change of position at that instant
- Slope of tangent to position-time graph

## Graphical Determination

### Process:

1. Take smaller and smaller time intervals around the point
2. Calculate average velocity for each interval
3. Find limiting value as  $\Delta t$  approaches zero
4. Slope of tangent = instantaneous velocity

**Example Analysis:** For  $x = 0.08t^3$  at  $t = 4s$ :

$\Delta t(s)$	$t_1(s)$	$t_2(s)$	$x_1(m)$	$x_2(m)$	$\Delta x(m)$	$\Delta x/\Delta t(m/s)$
2.0	3.0	5.0	2.16	10.00	7.84	3.92
1.0	3.5	4.5	3.43	7.29	3.86	3.86
0.5	3.75	4.25	4.22	6.14	1.92	3.84
0.1	3.95	4.05	4.93	5.31	0.38	3.84

**Result:** Limiting value = 3.84 m/s

## Calculus Method

For given position function:

$$x = a + bt^2$$
$$v = dx/dt = 2bt$$

**Example:**  $x = 8.5 + 2.5t^2$

- At  $t = 0$ :  $v = 0$  m/s
- At  $t = 2$ s:  $v = 10$  m/s
- Average velocity (2s to 4s) = 15 m/s

## Instantaneous Speed

**Definition:** Magnitude of instantaneous velocity **Key Points:**

- Always positive
  - Equal to  $|v|$  at any instant
  - Different from average speed over finite intervals
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## 2.3 ACCELERATION

### Historical Context

**Galileo's Contribution:**

- Debated: rate of change with distance vs time
- Concluded: rate of change with time is constant for free fall
- Established acceleration concept

## Average Acceleration

### Definition:

$$a = (v_2 - v_1)/(t_2 - t_1) = \Delta v/\Delta t$$

**SI Unit:**  $\text{m/s}^2$  **Graphical Meaning:** Slope of line connecting two points on v-t graph

## Instantaneous Acceleration

### Definition:

$$a = \lim(\Delta t \rightarrow 0) \Delta v/\Delta t = dv/dt$$

### Physical Meaning:

- Rate of change of velocity at specific instant
- Slope of tangent to v-t curve

## Types of Acceleration

1. **Positive Acceleration:**  $a > 0$
2. **Negative Acceleration (Deceleration):**  $a < 0$
3. **Zero Acceleration:**  $a = 0$  (uniform motion)

## Velocity-Time Graphs

### Case Analysis:

Case	Motion Direction	Acceleration	Graph Shape
(a)	Positive	Positive	Upward slope
(b)	Positive	Negative	Downward slope
(c)	Negative	Negative	Steeper downward
(d)	Changes at $t_1$	Negative	Through zero

### Position-Time Graph Characteristics

- **Positive acceleration:** Curves upward
- **Negative acceleration:** Curves downward
- **Zero acceleration:** Straight line

### Area Under v-t Curve

**Important Property:** Area under velocity-time curve = displacement

#### Proof for Constant Velocity:

- Rectangle: height =  $u$ , base =  $T$
- Area =  $u \times T$  = displacement

## 2.4 KINEMATIC EQUATIONS FOR UNIFORMLY ACCELERATED MOTION

### Fundamental Relationship

**For constant acceleration:**

$$v = v_0 + at \quad \dots (2.4)$$

## Derivation Using Graphical Method

**Area under v-t curve:**

$x = \text{Area of rectangle} + \text{Area of triangle}$

$$x = v_0 t + \frac{1}{2}(v - v_0)t$$

$$x = v_0 t + \frac{1}{2}at^2 \quad \dots (2.6)$$

## The Three Kinematic Equations

**Standard Form ( $x_0 = 0$ ):**

$$v = v_0 + at \quad \dots (2.9a)$$

$$x = v_0 t + \frac{1}{2}at^2 \quad \dots (2.9b)$$

$$v^2 = v_0^2 + 2ax \quad \dots (2.9c)$$

**General Form ( $x_0 \neq 0$ ):**

$$v = v_0 + at$$

$$x = x_0 + v_0 t + \frac{1}{2}at^2$$

$$v^2 = v_0^2 + 2a(x - x_0)$$

## Average Velocity Formula

$$\bar{v} = (v_0 + v)/2 \quad (\text{for constant acceleration only})$$

$$x = \bar{v}t$$

## Derivation Using Calculus Method

**Starting from definition:**

$$a = dv/dt$$

$$\int dv = \int a dt$$

$$v - v_0 = at$$

$$v = v_0 + at$$

**For displacement:**

$$v = dx/dt$$

$$\int dx = \int v dt = \int (v_0 + at)dt$$

$$x - x_0 = v_0t + \frac{1}{2}at^2$$

**For  $v^2$ -x relation:**

$$a = v(dv/dx)$$

$$\int v dv = \int a dx$$

$$\frac{1}{2}(v^2 - v_0^2) = a(x - x_0)$$

$$v^2 = v_0^2 + 2a(x - x_0)$$

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## 2.5 SOLVED EXAMPLES WITH DETAILED ANALYSIS

### Example 1: Vertical Motion

**Problem:** Ball thrown upward with 20 m/s from 25 m height **Given:**  $v_0 = +20$  m/s,  $y_0 = 25$  m,  $a = -g = -10$  m/s<sup>2</sup>

**Part (a): Maximum height Method:** Use  $v^2 = v_0^2 + 2a(y - y_0)$  with  $v = 0$



$$0 = (20)^2 + 2(-10)(y - 25)$$

$$y - y_0 = 20 \text{ m}$$

Maximum height reached = 20 m above launch point

### Part (b): Time to hit ground Method 1 - Two-stage approach:

- Time to reach maximum height:  $t_1 = v_0/g = 20/10 = 2 \text{ s}$
- Time to fall from max height to ground:

$$0 = 45 + 0 \cdot t_2 + \frac{1}{2}(-10)t_2^2$$

$$t_2 = 3 \text{ s}$$

- Total time =  $t_1 + t_2 = 5 \text{ s}$

### Method 2 - Direct approach:

$$y = y_0 + v_0 t + \frac{1}{2} a t^2$$

$$0 = 25 + 20t - 5t^2$$

$$5t^2 - 20t - 25 = 0$$

$$t = 5 \text{ s (taking positive root)}$$

### Example 2: Free Fall Analysis

#### Characteristics:

- Initial velocity:  $v_0 = 0$
- Acceleration:  $a = -g = -9.8 \text{ m/s}^2$
- Direction: vertically downward

#### Equations of Motion:

$$v = -gt$$

$$y = -\frac{1}{2}gt^2$$

$$v^2 = -2gy$$

### Graphs:

- Acceleration vs time: Constant negative
- Velocity vs time: Linear decrease
- Position vs time: Parabolic

### Example 3: Galileo's Law of Odd Numbers

**Statement:** Distances in successive equal time intervals are in ratio 1:3:5:7:...

**Proof:** For time intervals  $\tau, 2\tau, 3\tau, \dots$

$$\begin{aligned} \text{Distance in } n\text{th interval} &= y(n\tau) - y((n-1)\tau) \\ &= \frac{1}{2}g(n\tau)^2 - \frac{1}{2}g((n-1)\tau)^2 \\ &= \frac{1}{2}g\tau^2(n^2 - (n-1)^2) \\ &= \frac{1}{2}g\tau^2(2n - 1) \end{aligned}$$

**Ratio:**  $(2 \times 1 - 1):(2 \times 2 - 1):(2 \times 3 - 1):\dots = 1:3:5:7:\dots$

### Example 4: Stopping Distance

**Derivation:**  $v^2 = v_0^2 + 2ax$  with  $v = 0, a = -a$

$$0 = v_0^2 - 2ads$$

$$ds = v_0^2/(2a)$$

**Key Insight:** Stopping distance  $\propto v_0^2$

- Double speed → Four times stopping distance
- Critical for traffic safety regulations

### Example 5: Reaction Time Measurement

**Setup:** Ruler drop experiment **Given:**  $d = 21.0 \text{ cm} = 0.21 \text{ m}$ ,  $g = 9.8 \text{ m/s}^2$

**Solution:**

$$d = \frac{1}{2}gt^2$$

$$t = \sqrt{(2d/g)} = \sqrt{(2 \times 0.21/9.8)} = 0.21 \text{ s}$$

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## 2.6 RELATIVE VELOCITY

### Concept Introduction

**Definition:** Velocity of one object as observed from another moving object

**Mathematical Expression:**

$$v_{12} = v_1 - v_2$$

where  $v_{12}$  is velocity of object 1 relative to object 2

**Applications:**

- Motion analysis from different reference frames
  - Collision problems
  - Relative motion of vehicles
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# SUMMARY - KEY CONCEPTS

## 1. Motion Fundamentals

- Motion = change in position with time
- Reference frame dependency
- Point object approximation validity

## 2. Velocity Concepts

### Instantaneous Velocity:

$$v = \lim(\Delta t \rightarrow 0) \Delta x / \Delta t = dx/dt$$

- Slope of tangent to x-t graph
- Vector quantity with magnitude and direction

### Speed:

- Magnitude of velocity
- Always positive
- Instantaneous speed = |instantaneous velocity|

## 3. Acceleration Concepts

### Instantaneous Acceleration:

$$a = \lim(\Delta t \rightarrow 0) \Delta v / \Delta t = dv/dt$$

- Slope of tangent to v-t graph
- Can be positive, negative, or zero

## 4. Kinematic Equations

For constant acceleration:

$$v = v_0 + at$$

$$x = x_0 + v_0t + \frac{1}{2}at^2$$

$$v^2 = v_0^2 + 2a(x - x_0)$$

## 5. Graphical Analysis

- **x-t graph:** Slope gives velocity
  - **v-t graph:** Slope gives acceleration, area gives displacement
  - **a-t graph:** Area gives change in velocity
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## POINTS TO PONDER - CRITICAL INSIGHTS

### 1. Reference Frame Choice

- Origin and positive direction are arbitrary
- Must specify before assigning signs
- Consistency throughout problem is crucial

### 2. Acceleration Direction

- If speeding up:  $a \square$  same direction as  $v \square$
- If slowing down:  $a \square$  opposite direction to  $v \square$
- Independent of coordinate system choice

### **3. Sign Conventions**

- Sign of acceleration depends on chosen positive direction
- Same acceleration can appear positive or negative
- Example: gravity is  $-g$  if upward is positive

### **4. Zero Velocity $\neq$ Zero Acceleration**

- Object can be momentarily at rest with non-zero acceleration
- Example: ball at highest point of throw
- Velocity = 0, but acceleration =  $-g$

### **5. Equation Validity**

- Kinematic equations: constant acceleration only
- Velocity/acceleration definitions: always valid
- Must substitute values with correct signs

### **6. Mathematical Rigor**

- Instantaneous definitions are exact
- Kinematic equations are approximations for constant  $a$
- Real graphs are smooth (no sharp kinks)

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## **JEE/NEET SPECIFIC IMPORTANT POINTS**

### **High-Yield Topics**

#### **1. Kinematic Equations**

**Master these relationships:**

- When to use each equation
- Sign convention problems
- Multi-stage motion analysis

**2. Graphical Analysis****Key skills:**

- Interpreting x-t, v-t, a-t graphs
- Area and slope calculations
- Converting between different graphs

**3. Free Fall Problems****Standard scenarios:**

- Object dropped from rest
- Object thrown upward
- Object thrown downward
- Multi-stage analysis

**4. Relative Motion****Applications:**

- Rain and wind problems
- Vehicle collision analysis
- Motion in accelerated frames

## **Common Question Types**

### **1. Direct Application Problems**

- Given three quantities, find fourth
- Time-displacement relationships
- Velocity calculations

### **2. Graphical Problems**

- Sketch graphs from given information
- Extract information from graphs
- Area and slope calculations

### **3. Multi-Stage Problems**

- Motion with different accelerations
- Projectile-like problems
- Combined motion analysis

### **4. Real-World Applications**

- Traffic safety calculations
- Sports motion analysis
- Reaction time problems

## **Problem-Solving Strategy**

### **1. Setup Phase**

- Choose coordinate system



- Identify given and required quantities
- Determine appropriate equation

## **2. Calculation Phase**

- Substitute values with correct signs
- Solve algebraically before numerical substitution
- Check dimensional consistency

## **3. Verification Phase**

- Check if answer makes physical sense
  - Verify signs and magnitudes
  - Consider limiting cases
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# **MEMORY AIDS AND MNEMONICS**

## **Kinematic Equations**

**"VUT SAT V<sup>2</sup>"**

- $V = V_0 + AT$  (velocity-time)
- $S = UT + \frac{1}{2}AT^2$  (displacement)
- $V^2 = U^2 + 2AS$  (velocity-displacement)

## **Sign Convention**

**"Choose Once, Use Always"**

- Establish positive direction first

- Apply consistently throughout problem
- Acceleration and velocity signs depend on choice

## Graph Relationships

### "Slope Area Rules"

- x-t: Slope = velocity
  - v-t: Slope = acceleration, Area = displacement
  - a-t: Area = change in velocity
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## PRACTICE PROBLEMS FOR JEE/NEET

### Level 1: Basic Application

**Problem 1:** A car accelerates uniformly from rest to 60 km/h in 10 s. Find: (a) Acceleration (b) Distance covered

#### Solution:

- $v_0 = 0, v = 60 \text{ km/h} = 16.67 \text{ m/s}, t = 10 \text{ s}$
- $a = (v - v_0)/t = 1.67 \text{ m/s}^2$
- $s = v_0 t + \frac{1}{2}at^2 = 83.3 \text{ m}$

**Problem 2:** From v-t graph, if velocity changes linearly from 10 m/s to 30 m/s in 5 s: (a) Find acceleration (b) Find displacement

#### Solution:

- $a = (30 - 10)/5 = 4 \text{ m/s}^2$
- $s = \text{area of trapezium} = \frac{1}{2}(10 + 30) \times 5 = 100 \text{ m}$

## Level 2: Intermediate

**Problem 3:** A ball is thrown vertically upward with 20 m/s. Find: (a) Maximum height (b) Time of flight (c) Velocity after 3 s

**Solution:**

- (a) At max height,  $v = 0$ :  $v^2 = v_0^2 - 2gh \rightarrow h = 20.4 \text{ m}$
- (b) Total time  $= 2v_0/g = 4.08 \text{ s}$
- (c)  $v = 20 - 9.8(3) = -9.4 \text{ m/s}$

## Level 3: Advanced

**Problem 4:** Two trains approach each other with speeds 40 km/h and 50 km/h. When 2 km apart, both start decelerating at  $0.5 \text{ m/s}^2$  and  $0.3 \text{ m/s}^2$  respectively. Will they collide?

**Solution:** Requires relative motion analysis and meeting condition check.

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## ADVANCED TOPICS FOR JEE

### 1. Non-Uniform Motion

- Variable acceleration problems
- Integration and differentiation approach
- Piece-wise motion analysis

### 2. Relative Motion Applications

- Rain-umbrella problems
- River crossing scenarios
- Elastic collision analysis

### **3. Graphical Problem Types**

- Finding equations from graphs
- Motion description from multiple graphs
- Graph transformation problems

### **4. Limiting Cases**

- Very large acceleration limits
  - Zero acceleration cases
  - Instantaneous analysis
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## **ERROR ANALYSIS IN MOTION**

### **Common Mistakes**

#### **1. Sign Errors**

- Inconsistent coordinate system
- Wrong direction assignment
- Mixing up positive/negative

#### **2. Equation Selection**

- Using wrong equation for given information
- Forgetting constant acceleration requirement
- Misapplying multi-stage motion

#### **3. Unit Confusion**

- Mixing km/h and m/s
- Time unit inconsistencies
- Area calculation errors in graphs

## **Prevention Strategies**

1. **Always draw diagram** with coordinate system
  2. **List known/unknown** quantities clearly
  3. **Check dimensions** of final answer
  4. **Verify limiting cases** and physical reasonableness
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## **EXPERIMENTAL CONNECTIONS**

### **1. Galileo's Experiments**

- Inclined plane studies
- Free fall investigations
- Mathematical description of motion

### **2. Modern Applications**

- GPS technology (requires precise motion analysis)
- Automotive safety systems
- Sports performance analysis

### **3. Technology Integration**

- Motion sensors and data loggers
- Video analysis software

- Computer modeling of motion
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**EXAM SPRINT** - Master Motion in a Straight Line through focused study of velocity, acceleration, kinematic equations, and graphical analysis. Regular practice of numerical problems and conceptual understanding is essential for JEE/NEET success.

**Source:** NCERT Physics Class 11, Chapter 2 - Comprehensive coverage for competitive exam preparation